

# I618 Advanced Computer Science II (Part II)

12/21 11:00-12:30  
1/ 7 15:10-16:40  
○1/ 9 9:20-10:50  
1/11 11:00-12:30  
1/16 9:20-10:50

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**I will give you some report problems on January.**

# Algorithms on Interval/Chordal Graphs

- Some efficient algorithms on the graphs
  - based on the graph properties, especially;
    - [Thm 5] Every interval graph has a *compact representation* in  $[1..|V|]$ , and all maximal cliques appear on the representation.  
... we can solve many problems by “sweeping” from left to right.
    - [Thm 6] In a chordal graph, every *separator* is a *clique*.  
... which allows us to use “divide-and-conquer.”
    - [Thm 9] A chordal graph is an intersection graph of subtrees of a tree.  
... which generalizes the results on interval graphs;
      - each node of the tree *can* correspond to a maximal clique,
      - the number of nodes *can* be at most  $|V|$ .  
... which allows us “dynamic programming” on the tree.

The tree is called “clique tree,” but it requires more detailed analysis to make it “compact” since [Thm 9] does not construct a compact one.

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# Algorithms on Interval/Chordal Graphs

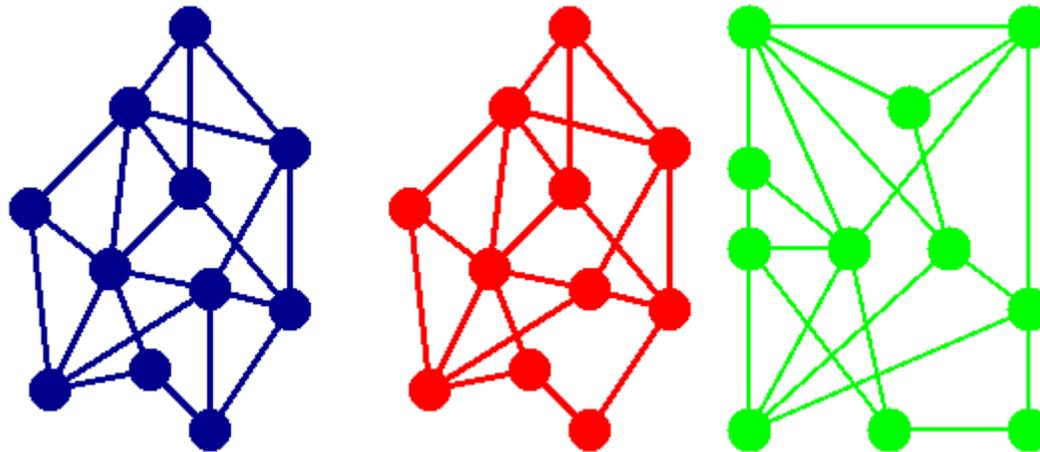
## ■ Basic problems

- graph isomorphism asks if two graphs are essentially “same”.
  - its difficulty is *hereditary*; superclass is more difficult and subclass is easier.
  - graph isomorphism is *hard* for chordal graphs (and its superclasses)
  - graph isomorphism is *linear time solvable* for interval graphs (and its subclasses)
- graph recognition determines if a given graph is in the class.
  - its difficulty is *not hereditary*; we need specified algorithm for each graph class
  - chordal graphs can be recognized in linear time
  - interval graphs can be recognized in linear time

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# Graph Isomorphism

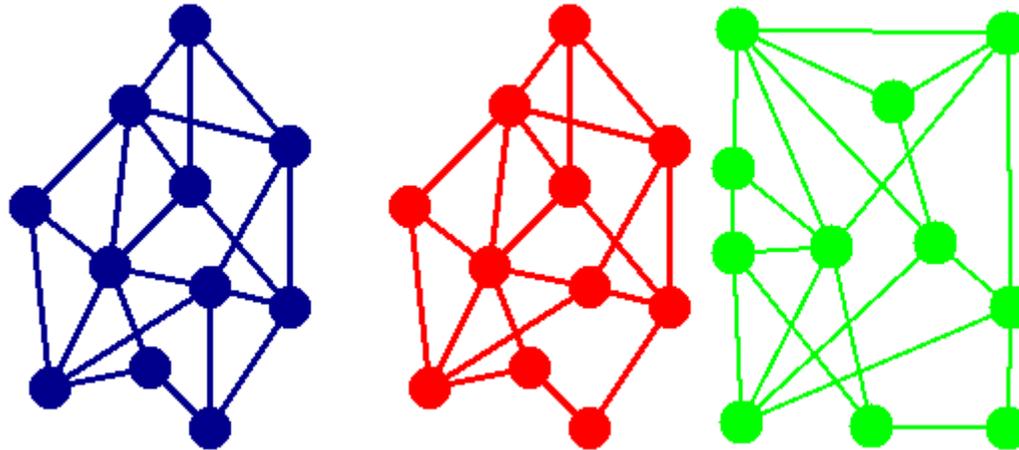
- The graph isomorphism problem
  - asks if there is a one-to-one mapping of vertex sets which keeps adjacency relationship.



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# Graph Isomorphism

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# Graph Isomorphism

- The graph isomorphism problem
  - asks if there is a one-to-one mapping of vertex sets which keeps adjacency relationship.
- The GI problem is very natural basic problem.
  - It is in  $\mathcal{NP}$ , but it is not known if it is in  $\mathcal{P}$  or  $\mathcal{NP}$ -complete
    - long standing open problem
    - *many* researchers feel it is easier than  $\mathcal{NP}$ -complete problems
    - one candidate *between*  $\mathcal{P}$  and  $\mathcal{NP}$ -complete problems.
  - Hence we introduce ‘GI-completeness’;
    - the GI problem is *GI-complete* on a graph class  $\mathcal{C}$  if the GI problem is still as hard as the usual one even on the class  $\mathcal{C}$ .

# Graph Isomorphism

- The GI problem is very natural basic problem.
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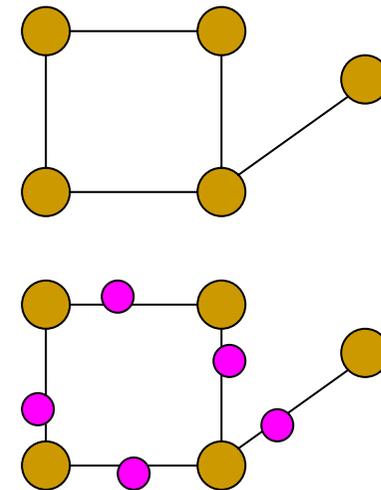
[Example 1] The GI problem for bipartite graphs is GI-complete.

(Proof) For any given graph  $G=(V,E)$ , we construct  $G'=(V',E')$  as follows;

1.  $V':=V \cup E$
2.  $E':=\{\{e,v\} | v \in e \in E\}$

It is easy to see that

1.  $G'$  is bipartite for any  $G$ , and
2.  $G_1'$  and  $G_2'$  are isomorphic iff  $G_1$  and  $G_2$  are isomorphic. □



# Graph Isomorphism

- The GI problem is very natural basic problem.
  - For our graph classes...
    - The GI problem on interval graphs is solvable in linear time.
    - Chordal graphs are GI-complete.

[Theorem 10] The GI problem for trees can be solved in linear time.

(Proof) Exercise! (Or report?) □

[Note] Theorem 10 is strongly related to the GI-problem for several graph classes including interval graphs.

[Today's First Goal]

1. The results for interval graphs are postponed after recognition.
2. GI-completeness of chordal graphs.

# Graph Isomorphism

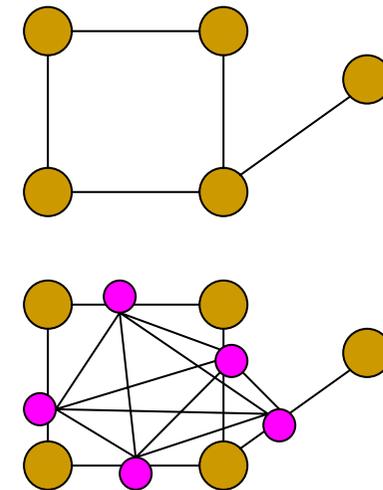
## ■ The GI problem for chordal graphs

[Theorem 11] The GI problem for chordal graphs is GI-complete.

(Proof) It is sufficient to show that the GI problem for general graphs can be reduced to the GI problem for chordal graphs by a polynomial time reduction.

Let  $G=(V,E)$  be a given (general) graph, and  $G'=(V',E')$  be a graph constructed as follows;

1.  $V':=V \cup E$
2.  $E'$  consists of
  1.  $\{u,e\}, \{v,e\}$  if  $e=\{u,v\}$  in  $E$ ,
  2.  $\{e_1,e_2\}$  for all  $e_1, e_2$  in  $E$ .



# Graph Isomorphism

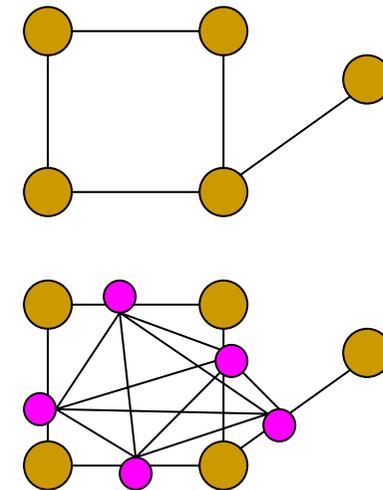
- The GI problem for chordal graphs

[Theorem 11] The GI problem for chordal graphs is GI-complete.

(Proof) It is sufficient to show that the GI problem for general graphs can be reduced to the GI problem for chordal graphs by a polynomial time reduction.

It is sufficient to show that

1.  $G'$  is a chordal graph, and
2.  $G_1$  and  $G_2$  are isomorphic iff so are  $G_1'$  and  $G_2'$ .



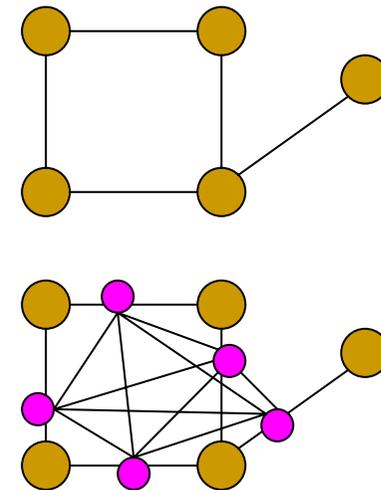
# Graph Isomorphism

- The GI problem for chordal graphs

[Theorem 11] The GI problem for chordal graphs is GI-complete.

(Proof) It is sufficient to show that the GI problem for general graphs can be reduced to the GI problem for chordal graphs by a polynomial time reduction.

1.  $G'$  is a chordal graph;  
any cycle  $C=(v_1, v_2, \dots, v_k, v_1)$  of length at least 4 contains at least two vertices in  $E$ , which are joined by a chord.



# Graph Isomorphism

## ■ The GI problem for chordal graphs

[Theorem 11] The GI problem for chordal graphs is GI-complete.

(Proof) 2.  $G_1$  is isomorphic to  $G_2$  iff so are  $G_1'$  and  $G_2'$

$\Leftrightarrow G$  can be reconstructed from  $G'$  up to isomorphism.

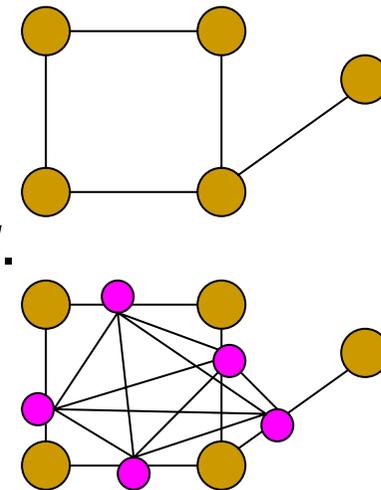
For given  $G'=(V',E')$ ,

1.  $E$  can be determined by the set of vertices

1.  $E$  induces a clique

2. each of them have two neighbors in  $V'-E$ .

2.  $V$  is determined by  $V'-E$ , and  $G$  can be reconstructed uniquely.  $\square$



# Graph Isomorphism

- The GI problem for chordal graphs

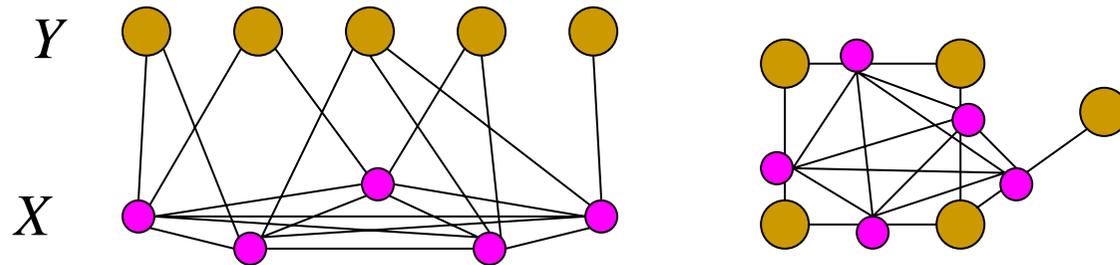
[Theorem 11] The GI problem for chordal graphs is GI-complete.

[Note] The chordal graph in the proof of [Theorem 11] is a special chordal graph  $G=(V,E)$ ;

- $V$  can be partitioned into two sets  $X$  and  $Y$  such that  $G[X]$  induces a clique and  $G[Y]$  induces an independent set.

Such graphs are called “*split graphs*.”

[Corollary 2] The GI problem for split graphs is GI-complete.



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# Algorithms on Interval/Chordal Graphs

- The graph recognition problem
  - difficulty is *not hereditary*; we need specified algorithm for each graph class
    - chordal graphs can be recognized in linear time
    - interval graphs can be recognized in linear time
- Very rough history...
  - chordal graph
    - Lexicographically breadth first search
    - Maximum cardinality search
  - interval graph
    - based on canonical tree representations
    - based on LexBFS
    - based on modular decompositions

# Recognition of Interval/Chordal Graphs

- Rough history of the graph recognition...

- chordal graph... linear time recognition by

- Lexicographically breadth first search (**LexBFS**)

- [Rose, Tarjan, Lueker 1976]

- Maximum cardinality search

- [Tarjan, Yannakakis 1984]

Those two algorithms are so “good” that we have no chance to “improve”

- interval graph... linear time recognition by

- 1970s-80s; based on canonical tree representations

- [Booth, Lueker 1976], [Lueker, Booth 1979], [Korte, Möhring 1989]

- 1990s; based on **LexBFS**

- several papers..., [Corneil, Olariu, Stewart 1998]

- 2000-?; based on modular decompositions

- some papers..., [McConnell, de Montgolfier 2005]

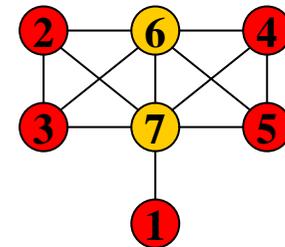
Those algorithms have more detailed history, which will be explained later (not today)...

# Recognition of a Chordal Graph

- Rough history of the graph recognition of chordal graphs
  - Lexicographically breadth first search (**LexBFS**)
    - by [Rose, Tarjan, Lueker 1976]
    - LexBFS is used to recognize several graph classes including
      - chordal graphs, interval graphs, cographs, Ptolemaic graphs, unit interval graphs, ...
    - A survey for (only?) LexBFSs can be found in [Corneil 2004], which is an invited talk at WG 2004.
  - Maximum cardinality search (**MCS**)
    - by [Tarjan, Yannakakis 1984]
    - A relatively *few* related results are known about MCS.
  - LexBFS and MCS are simple for implementation, have good property, and hence they are well investigated.

# Recognition of a Chordal Graph

- LexBFS and MCS are a kind of “search” algorithms.
  - Both algorithms find *reverse* of a PEO as follows;
    1. put any vertex as  $v_n$ ;
    2. for each  $i=n-1, n-2, \dots, 1$ 
      1. find the next vertex and put it as  $v_i$



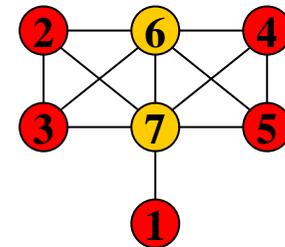
[Observation 1] Any vertex can be the last vertex of a PEO on a chordal graph.

(Proof) Exercise!! (Hint: consider the tree model.)

[Point] How can we find the next vertex?

# Recognition of a Chordal Graph

- LexBFS and MCS are a kind of “search” algorithms.
  - Both algorithms find *reverse* of a PEO as follows;
    1. put any vertex as  $v_n$ ;
    2. for each  $i=n-1, n-2, \dots, 1$ 
      1. find the **next** vertex and put it as  $v_i$



[Point] How can we find the **next** vertex?

[MCS] the next vertex  $v_i$  is determined by

$$v_i := \max |N(v_i) \cap \{v_{i+1}, v_{i+2}, \dots, v_n\}|,$$

which is the reason why we call it

“maximum cardinality” search.

(Ties are broken in any way.)

